

## Adjustment of robots switches

- Put the photometer with his robot plugged in test mode

Pw on 3 then press Word (white button)

Mon

Ram

Mod

20 => 00 pass to 20 => 02

Rtn

Rtn

Rtn (the window switch off)

Rtn (the window switch on)

Then

Press Scn

Press red button until Park

Then press Go and the robot make a park position and you can read the values H and V

Ex: **H135**① **072**② **V126**① **078**②

H for the azimuth and V for the zenith

Pour un bon réglage il faut :

| ① - ② | < 40 (+/-10 au max)

70 < ② < 90

If not ok, adjust or change the switches

Open the motor part of the foot of the robot (There are 6 screws for each motor block) -Pict1-

Adjusted the switch with the couple of screws near the motor. -Pict2-



-Picture 1-



-Picture 2-