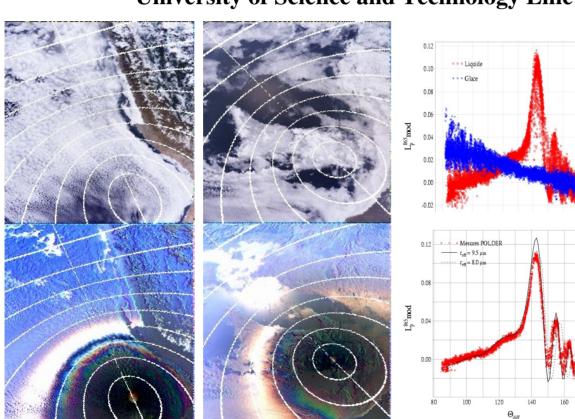
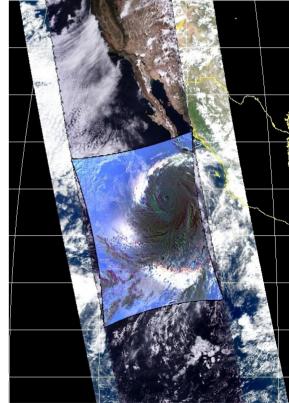
# **Remote Sensing of Clouds from Polarization**

What polarization can tell us about clouds... and what not?

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## **OUTLINE**

- What this talk is about :
  - passive measurement of polarized reflected sunlight
  - cloud remote sensing from polarization multiangle measurements
  - cloud microphysic (phase, shape, size distribution)
  - what is possible with polarization ...
  - ... what we can not or should not do with polarization
  - ... and what we may be able to do in a near future.
- What it is not about :
  - active remote sensing (lidar, radar)
  - multiangle without polarization ...
  - ... or polarization without multiangle.



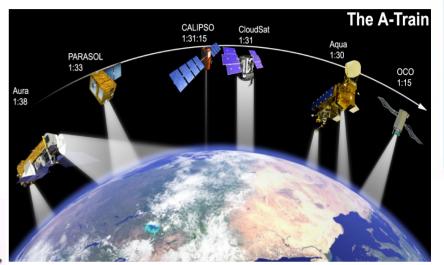


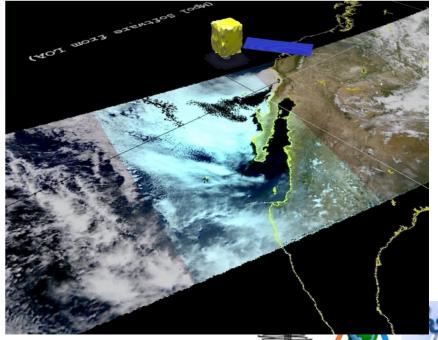


## Context & Instrumental Background



- CNES/LOA instrument, Parasol launched Dec. 2004
  - ~ 705 km polar orbits, ascending (13:30 a.m.)
- Sensor Characteristics
  - 10 spectral bands ranging from 0.443 to 1.020  $\mu m$
  - 3 polarised channels
  - Wide FOV CCD Camera with 1800 km swath width
  - +/- 43 degrees cross track
  - +/- 51degrees along track
  - Multidirectionnal observations (up to 16 directions)
  - Spatial resolution : 6x7 km
  - No onboard calibration system Inflight vicarious calibration :
    - 2-3% absolute calibration accuracy
    - -1% interband -0.1% interpixel over clouds





What we think we can do ...





# **Past Application to Clouds Remote Sensing**

### Polarization by clouds

D. Deirmendjian - Appl. Opt, 1964, J. E. Hansen - Journal of Atmos. Sci., 1971

## Cloud phase

Goloub et al (2000), Riedi et al (2001)

### Liquid Cloud Microphysic

Bréon and Goloub (1998), Bréon and Doutriaux (2005)

## Ice Cloud Microphysic

Chepfer et al (2001), Liou and Takano (2002), Baran and Labonnote (2006)

#### **Oriented Particles Detection**

Chepfer et al (1999), Bréon and Dubrulle (2004), Noël et Chepfer (2004)

## **Cloud Top Pressure**

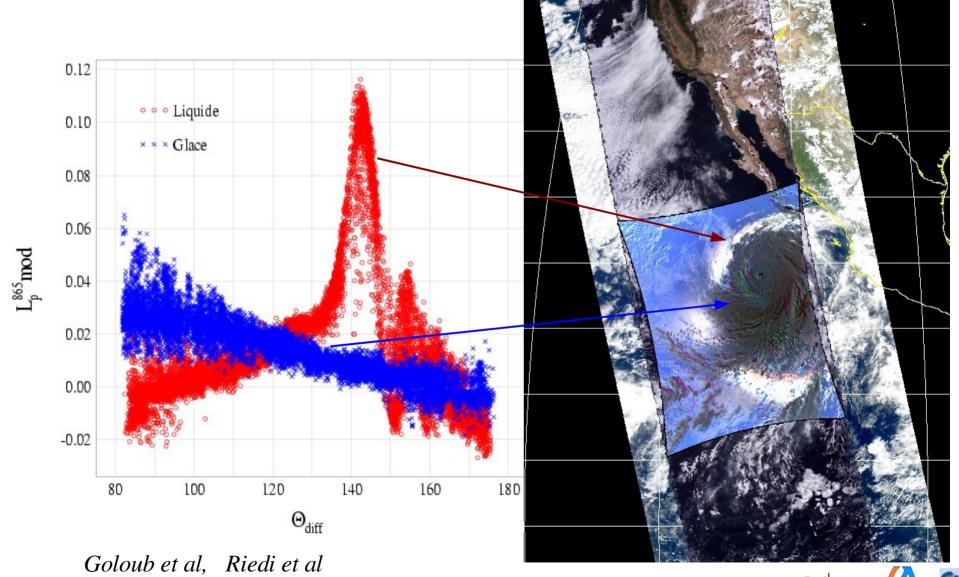
Buriez et al (1997), Vanbauce et al (2002)





# **Cloud Top Thermodynamic Phase**

Principle: particle shape discrimination spherical vs non sphe.



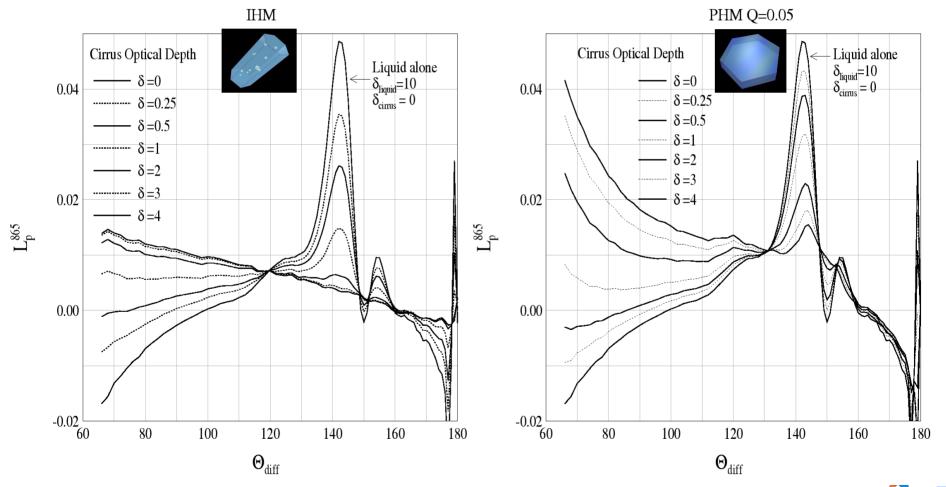


# **Cloud Top Thermodynamic Phase**

## How deep do we go inside clouds using polarization measurements?

Multilayer Systems: Cirrus over liquid cloud.

Liquid cloud can be « seen » up to cirrus OD of 2.0









## Cloud thermodynamic phase

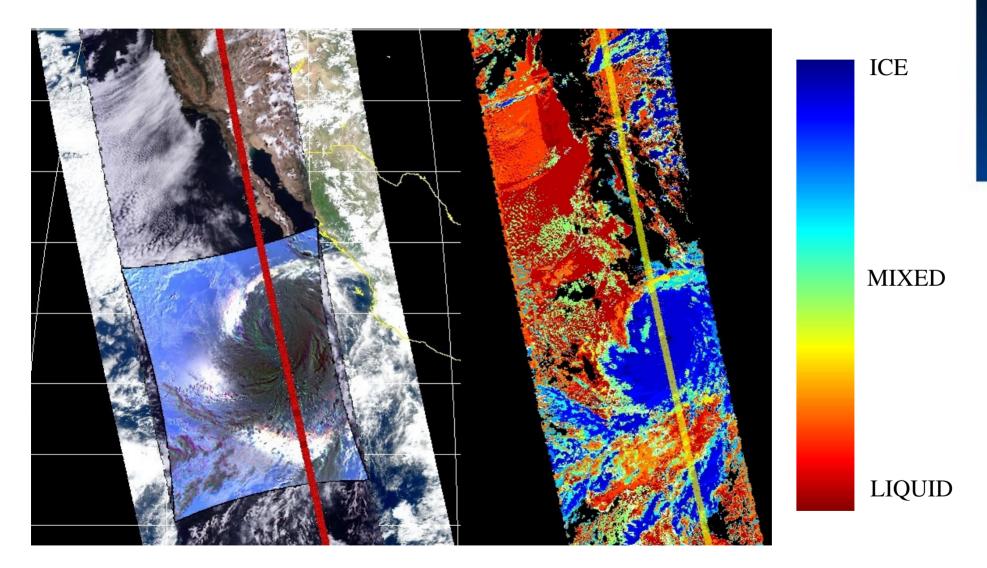
Combination of information on particle shape and absorption properties A-Train analysis: combining POLDER and MODIS to infer cloud phase

Thermal IR Bispectral **POLARIZATION SWIR/VIS Ratio UNKOWN** LIQUID



## Cloud thermodynamic phase

Combination of information on particle shape and absorption properties A-Train analysis: combining POLDER and MODIS to infer cloud phase



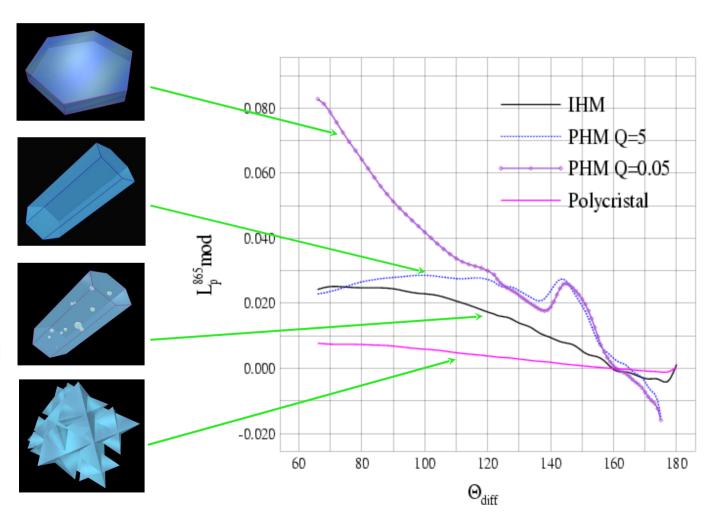
Riedi et al, 2007 (to be submitted to JGR)





# Principle: Polarized Phase function of single particle is strongly influenced by particle shape.

Computation of polarized reflectance for uniform layer ice cloud with single particle



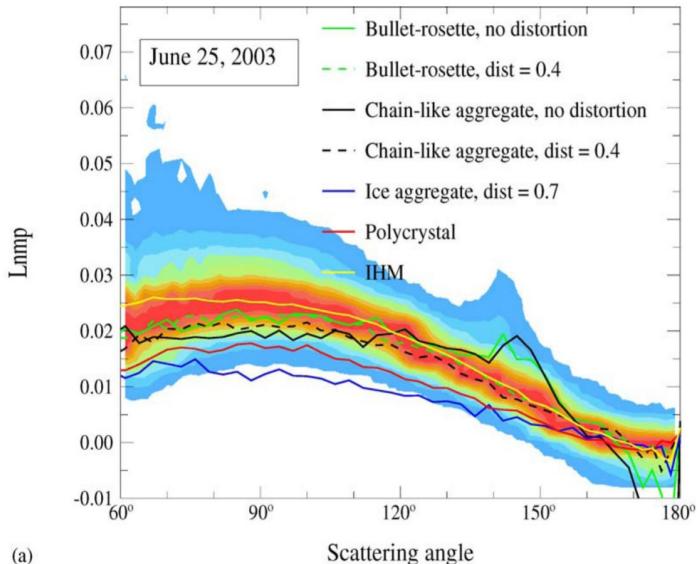
Can be used to derive particle shape (Chepfer et al, 1998).

How representative of real cloud with size and shape distribution?





## Modelled VS observed global mean polarized signature of ice clouds



Can also look for a mean equivalent model representative of an average ice cloud.

Labonnote et al (2001) demonstrated the Inhomogeous Hexagonal Model (IHM) can be used to fit well both total and polarized multiangle reflectances from POLDER.

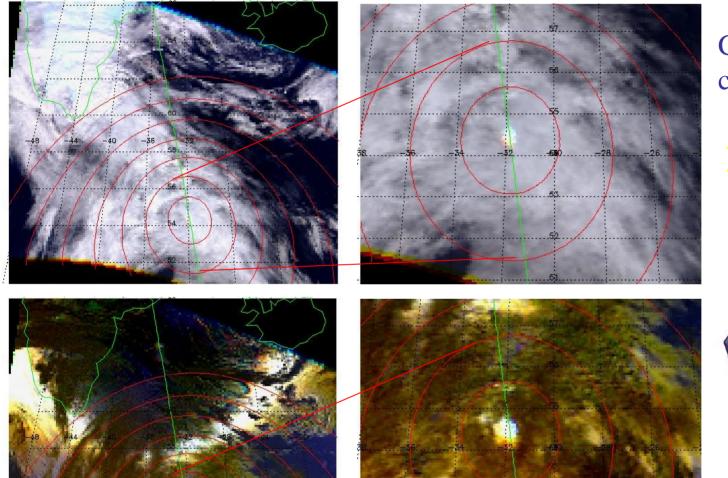
Figure from : A. J. Baran and L. C-Labonnote, JOSRT (2006)







Specular reflection on Oriented Plates in Ice clouds



Classical three color composite

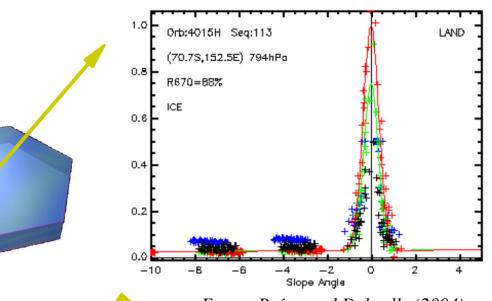






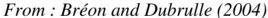


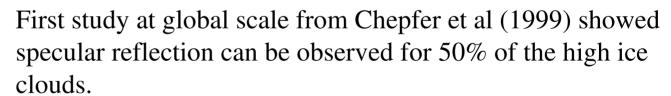
## Specular reflection on Oriented Plates in Ice clouds



Width and intensity of specular peak depends on particle size, concentration and distribution of tilt angle.

Directional signature of oriented plates can be use to infer characteristic tilt angle and particle concentration





Noel and Chepfer (2004), Bréon and Dubrulle (2004), using full RT or approximate calculation both agreed on:

- -the maximum tilt angle (typical  $1^{\circ}$ , maximum  $2^{\circ}$  to  $3^{\circ}$ )
- the very small fraction of oriented plates necessary to

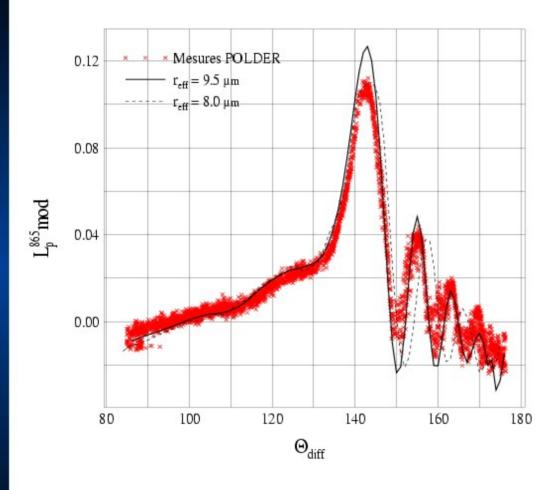




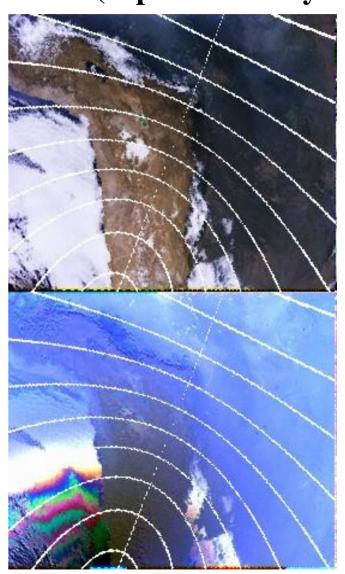


Principle: use of angular features above 140° (supernumerary bows).

Cloud Droplet Distribution: effective radius and variance



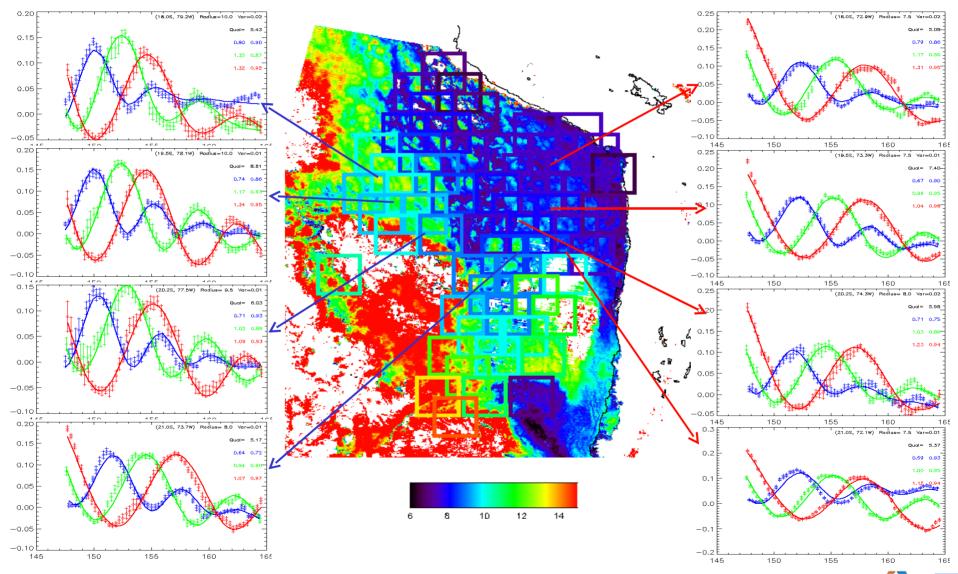








## **Comparison with MODIS retrievals**

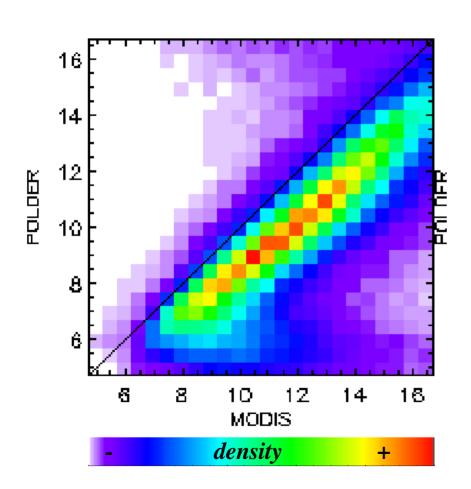


From: Bréon et Doutriaux, JAS (2005)



# **Liquid Cloud Droplet Effective Size Distribution**Comparison with MODIS retrievals

Comparison between POLDER and MODIS « effective » radii over ocean



Correlation is good but there is an apparent 2 microns bias between POLDER and MODIS retrievals.

POLDER sees smaller droplets than MODIS.

POLDER "less sensitive to biases and errors resulting from cloud heterogeneity, assumptions on the size distribution" when retrieval is possible <u>according to authors</u>.

#### **Questions:**

Is this real?

Is one of them correct? none? both?

From: Bréon et Doutriaux, JAS (2005)







Things we should consider carefully ...





# What have we learned from previous studies?

Polarization comes from single scattering so that phase function angular features are conserved in polarized reflectance.

Polarization provides information from the top (or edges) of the cloud

Polarization can provide different (not better, just different!) information than spectral observations.

Polarization yields more or less useful information depending on the range of accessible scattering angle.

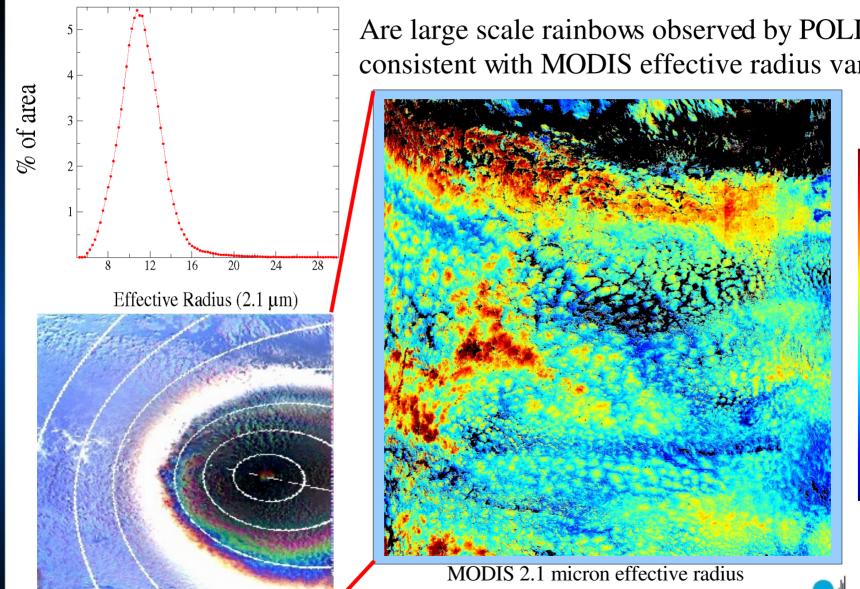
Polarization saturates for cloud OT greater than 2.0: relatively thin, thick or very thick clouds contribute equally to polarized radiance but not to total radiance!

A small portion of particles can produce a significant polarized signal.





Considerations on the use of polarization for droplets size retrieval





## Considerations on the use of polarization for droplets size retrieval

There is an **apparent** discrepancy between observation of extended rainbow features and variability observed in MODIS data.

#### Facts about liquid cloud microphysic:

- non uniform size distribution occur for various reasons in cloud fields at small or large scale. There can be :
- \* horizontal or vertical heterogeneities
- \* bimodal size distribution : for example when remaining aerosols rising with droplets get activated higher in the cloud
- \* small scales variability: in situ measurements show variation at high spatial frequency with pockets of small droplets, etc...
- relation between Reff and Veff is not completely clear but different processes can contribute to a positive correlation between them (Veff increases with Reff)

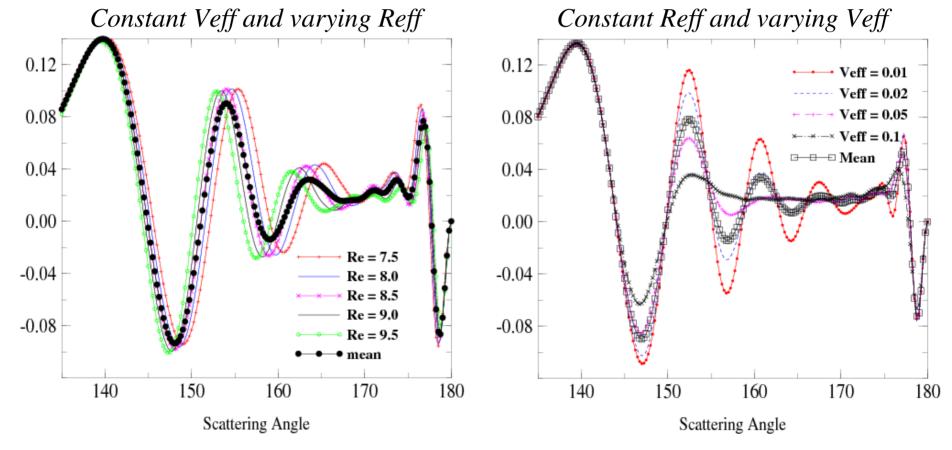
## What is the impact on polarization based retrievals?





## Considerations on the use of polarization for droplets size retrieval

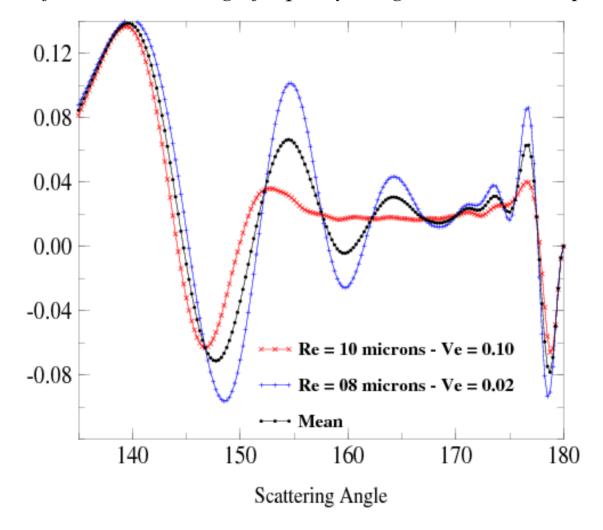
Mixing different distribution: impact on the phase function Mean phase function resulting of equally weighted phase function with:





# Liquid Cloud Droplet Effective Size Distribution Considerations on the use of polarization for droplets size retrieval

Mixing different distribution: impact on the phase function Mean phase function resulting of equally weighted individual phase function





# **Liquid Cloud Droplet Effective Size Distribution**Potential artifact to consider

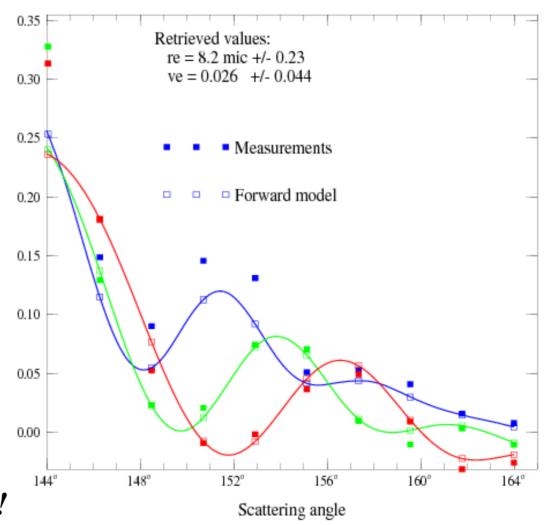
### Sensitivity study principle:

- compute the signal observed over a cloud with non homogeneous size distribution (can be horizontal heterogeneities, bimodal size distribution, etc...). Here we consider one half of the pixel covered with re = 8, the other with re = 12 microns
- select about 10 directions in each spectral bands and add some noise to create realistic synthetic measurements
- perform an inversion using a variational method

Results: the retrieved value is very close to the 8 microns part!

Riedi et Labonnote, 2007 (to be submitted to JAS)

Mixing (re=8,ve=0.02; re=12,ve=0.1) - ratio = 0.5





### **Partial Conclusions**

Polarization arises primarily from single scattering, hence it brings information from the top (or edges) of the cloud layers

Polarization saturates for cloud OT greater than 2.0: relatively thin, thick or very thick clouds contribute equally to polarized radiance but not to total radiance!

Small fractions of specific particles can contribute significantly to polarization signal

As for aerosol, polarization may be sensitive to the smallest droplets which contribute significantly to the signal.

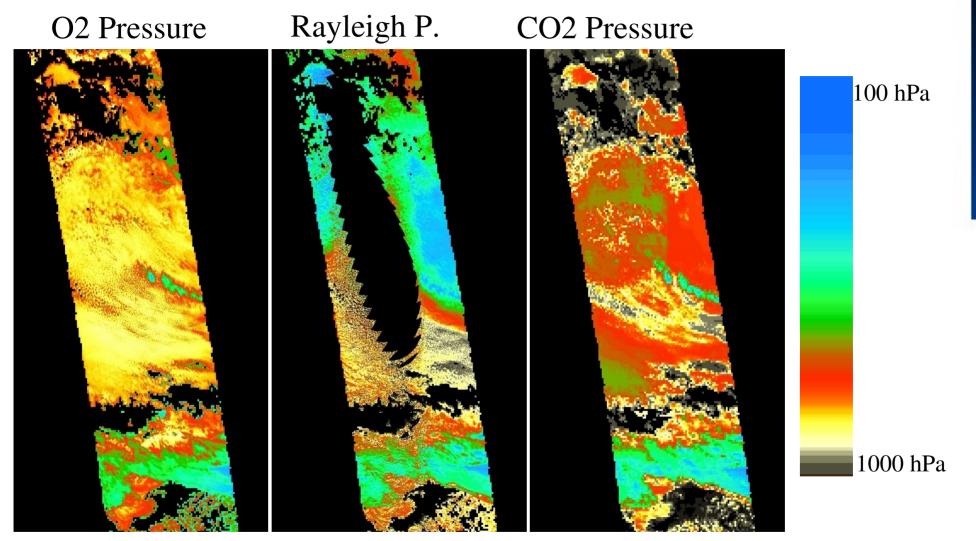
Information derived from polarization need to be considered carefully: retrievals are also subject to potential biases which need to be understood and recognized

# What is next step?



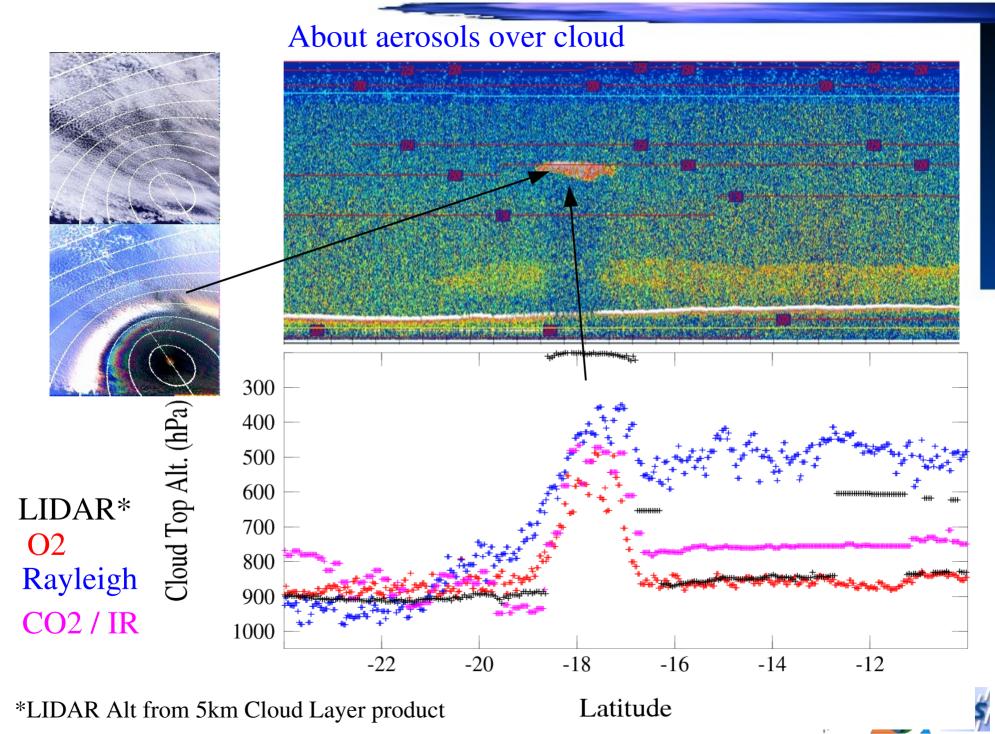


## About aerosols over cloud

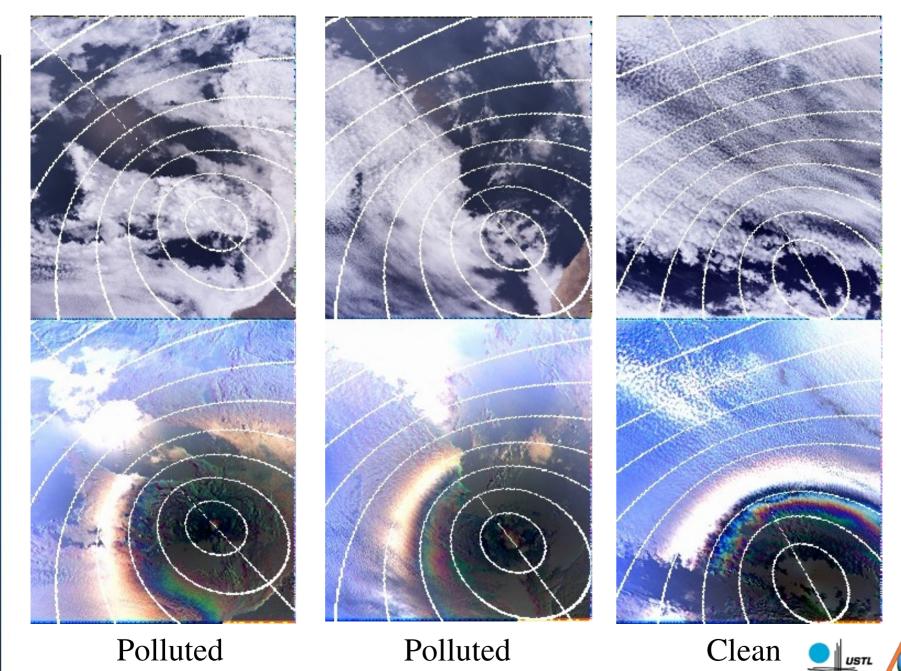


Presence of aerosol over a stratocumulus cloud layer causes strong divergence in the retrieved cloud top altitude from O2 band, Rayleigh and CO2 slicing methods.

-> Polarization is very sensitive to aerosols.



## About aerosols over cloud



## Aerosol layers over extended cloud fields

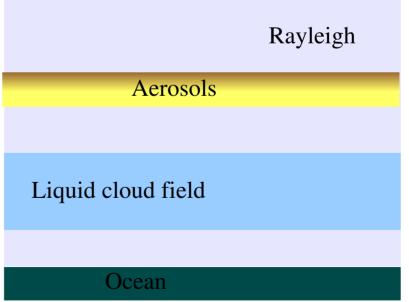
Can we derive information on aerosols using cloud are a « source » of polarized light?

Cloud -  $r_0 = 12 \mu m$ ;  $v_0 = 0.1$ 0.6 No aerosol 0.5  $\tau_{\rm aero}=0.2$  $\tau_{\text{aero}} = 0.5$ 0.4  $Rp^*$ 0.3 0.2 0.1 145° 140° 150°

Why is the primary rainbow turning brown?

Simulation of an aerosol absorbing layer over a liquid cloud (OT = 5)

The relative contribution of the red channel increases with aerosol optical thickness







Scattering angle

## Aerosol layers over extended cloud fields

Can we derive information on aerosols using cloud as a « source » of polarized light?

#### **Basis**

Use the rainbow as a "source" of polarized light and measure extinction through the aerosol layer

$$R_p^{TOA} = R_p^{Cloud} \exp^{-\tau/\mu} + R_p^{Aerosol + Rayleigh}$$

Use a band where the aerosol contribution is the lowest to retrieve cloud properties and recompute the signal for other 2 bands to get aerosol layer information.

Iterate using aerosol information previously retrieved to improve initial cloud signal estimate.

#### **Advantages**

The cloud signal can be determined consistently for the 3 bands.

Rayleigh contribution is reduced in the rainbow region

Knowing the cloud optical thickness is not necessary as long as the cloud is thick enough for polarization signal to saturate (> 2.0)

Rayleigh

Aerosols

Liquid cloud field

Ocean





# **Conclusions and Perspectives**

As early recognized, there is no doubt polarization contains information on cloud microphysic because the polarized phase function is very sensitive to particle shape.

Polarization multiangle measurements have been used to retrieve properties of both liquid and ice clouds.

Polarization arises primarily from single scattering, hence it brings information from the top or edges of the clouds where processes are not very well understood and where interaction between aerosols and clouds are important.

Small fractions of specific particles can contribute significantly to polarization signal



# **Conclusions and Perspectives**

Information derived from polarization need to be considered carefully: retrievals are also subject to potential biases which need to be understood and recognized

Differences between polarization and spectral based retrievals could carry new information on cloud microphysic variability.

As for aerosols, polarization seems to be sensitive to the «small mode» of droplets distribution.

Clouds could be used to retrieve information on aerosols: the so-called 13<sup>th</sup> indirect effect!! (*Labonnote and Riedi – In preparation - 2007*)

As far as polarization is concerned, this is definitely not the END ...



# But I'll stop here anyway ... THANKS FOR YOUR ATTENTION.

